

1 On nonpermutational transformation semigroups 2 with an application to syntactic complexity

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5 **Abstract.** We give an upper bound of $n((n-1)! - (n-3)!)$ for the possi-
6 ble largest size of a subsemigroup of the full transformational semigroup
7 over n elements consisting only of nonpermutational transformations. As
8 an application we gain the same upper bound for the syntactic complex-
9 ity of (generalized) definite languages as well.

10 1 Introduction

11 A language is generalized definite if membership can be decided for a word by
12 looking at its prefix and suffix of a given constant length. Generalized definite
13 languages and automata were introduced by Ginzburg [6] in 1966 and further
14 studied in e.g. [4,5,13,15]. This language class is strictly contained within the
15 class of star-free languages, lying on the first level of the dot-depth hierarchy [1].
16 This class possess a characterization in terms of its syntactic semigroup [12]:
17 a regular language is generalized definite if and only if its syntactic semigroup
18 is locally trivial if and only if it satisfies a certain identity $x^\omega y x^\omega = x^\omega$. This
19 characterization is hardly efficient by itself when the language is given by its
20 minimal automaton, since the syntactic semigroup can be much larger than the
21 automaton (a construction for a definite language with state complexity – that
22 is, the number of states of its minimal automaton – n and syntactic complexity –
23 that is, the size of the transition semigroup of its minimal automaton – $|e(n-1)!|$
24 is explicit in [2]). However, as stated in [14], Sec. 5.4, it is usually not necessary to
25 compute the (ordered) syntactic semigroup but most of the time one can develop
26 a more efficient algorithm by analyzing the minimal automaton. As an example
27 for this line of research, recently, the authors of [9] gave a nice characterization
28 of minimal automata of piecewise testable languages, yielding a quadratic-time
29 decision algorithm, matching an alternative (but of course equivalent) earlier
30 (also quadratic) characterization of [17] which improved the $\mathcal{O}(n^5)$ bound of [16].

31 There is an ongoing line of research for syntactic complexity of regular languages.
32 In general, a regular language with state complexity n can have a syntactic
33 complexity of n^n , already in the case when there are only three input letters.
34 There are at least two possible modifications of the problem: one option is to
35 consider the case when the input alphabet is binary (e.g. as done in [7,10]). The

second option is to study a strict subclass of regular languages. In this case, the syntactic complexity of a class \mathcal{C} of languages is a function $n \mapsto f(n)$, with $f(n)$ being the maximal syntactic complexity a member of \mathcal{C} can have whose state complexity is (at most) n . The syntactic complexity of several language classes, e.g. (co)finite, reverse definite, bifix-, factor- and subword-free languages etc. is precisely determined in [11]. However, the exact syntactic complexity of the (generalized) definite languages and that of the star-free languages (as well as the locally testable or the locally threshold testable languages) is not known yet.

In this note we give an upper bound for the maximal size of a subsemigroup of T_n , the transformation semigroup of $\{1, \dots, n\}$, consisting of “nonpermutational” transformations only. These are exactly the (transformation) semigroups satisfying the identity $yx^\omega = x^\omega$. It is known that a language is definite iff its syntactic semigroup satisfies the same identity; thus as a corollary we get that the same bound is also an upper bound for the syntactic complexity of definite languages.

We also give a forbidden pattern characterization for the generalized definite languages in terms of the minimal automaton, and analyze the complexity of the decision problem whether a given automaton recognizes a generalized definite language, yielding an **NL**-completeness result (with respect to logspace reductions) as well as a deterministic decision procedure running in $\mathcal{O}(n^2)$ time (on a RAM machine). Analyzing the structure of their minimal automata we conclude that the syntactic complexity of generalized definite languages coincide with that of definite languages.

2 Notation

When $n \geq 0$ is an integer, $[n]$ stands for the set $\{1, \dots, n\}$. For the sets A and B , A^B denotes the set of all functions $f : B \rightarrow A$. When $f \in A^B$ and $C \subseteq B$, then $f|_C \in A^C$ denotes the restriction of f to C . When A_1, \dots, A_n are disjoint sets, A is a set and for each $i \in [n]$, $f_i : A_i \rightarrow A$ is a function, then the *source tupling* of f_1, \dots, f_n is the function $[f_1, \dots, f_n] : (\bigcup_{i \in [n]} A_i) \rightarrow A$ with $a[f_1, \dots, f_n] = af_i$

$[f_1, \dots, f_n]$: source
tupling for the unique i with $a \in A_i$.

T_n is the transformation semigroup of $[n]$ (i.e. $[n]^{[n]}$), where composition is understood as $p(fg) := (pf)g$ for $p \in [n]$ and $f, g : [n] \rightarrow [n]$ (i.e., transformations of $[n]$ act on $[n]$ from the right to ease notation in the automata-related part of the paper). Elements of T_n are often written as n -ary vectors as usual, e.g. $f = (1, 3, 3, 2)$ is the member of T_4 with $1f = 1$, $2f = 3$, $3f = 3$ and $4f = 2$.

When $f : A \rightarrow A$ is a transformation of a set A , and X is a subset of A , then Xf denotes the subset $\{xf : x \in X\}$ of A .

nonpermutational
function
 NP_n

1 A transformation $f : A \rightarrow A$ of a (finite) set A is *nonpermutational* if $Xf = X$
2 implies $|X| = 1$ for any nonempty $X \subseteq A$. Otherwise it's *permutational*. NP_n
3 stands for the set of all nonpermutational transformations of $[n]$.

4 Another class of functions used in the paper is that of the *elevating* functions:
5 for the integers $0 < k \leq n$, a function $f : [k] \rightarrow [n]$ is elevating if $i \leq if$ for each
6 $i \in [k]$ with equality allowed only in the case when $i = n$ (note that this also
7 implies $k = n$ as well).

elevating function

8 We assume the reader is familiar with the standard notions of automata and
9 language theory, but still we give a summary for the notation.

10 An *alphabet* is a nonempty finite set Σ . The set of *words* over Σ is denoted Σ^* ,
11 while Σ^+ stands for the set of *nonempty words*. The *empty word* is denoted ε .
12 A *language* over Σ is an arbitrary set $L \subseteq \Sigma^*$ of Σ -words.

13 A (finite) *automaton* (over Σ) is a system $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ where Q is the
14 finite set of states, $q_0 \in Q$ is the start state, $F \subseteq Q$ is the set of final (or accepting)
15 states, and $\delta : Q \times \Sigma \rightarrow Q$ is the transition function. The transition function δ
16 extends in a unique way to a right action of the monoid Σ^* on Q , also denoted δ
17 for ease of notation. When δ is understood, we write $q \cdot u$, or simply qu for $\delta(q, u)$.
18 Moreover, when $C \subseteq Q$ is a subset of states and $u \in \Sigma^*$ is a word, let Cu stand
19 for the set $\{pu : p \in C\}$ and when L is a language, $CL = \{pu : p \in C, u \in L\}$.
20 The *language recognized by* \mathbb{A} is $L(\mathbb{A}) = \{x \in \Sigma^* : q_0x \in F\}$. A language is
21 *regular* if it can be recognized by some finite automaton.

22 The state $q \in Q$ is *reachable* from a state $p \in Q$ in \mathbb{A} , denoted $p \preceq_{\mathbb{A}} q$, or just
23 $p \preceq q$ if there is no danger of confusion, if $pu = q$ for some $u \in \Sigma^*$. An automaton
24 is *connected* if its states are all reachable from its start state.

25 Two states p and q of \mathbb{A} are *distinguishable* if there exists a word $u \in \Sigma^*$ such
26 that exactly one of pu and qu belongs to F . In this case we say that u *separates*
27 p and q . A connected automaton is called *reduced* if each pair of distinct states
28 is distinguishable.

29 It is known that for each regular language L there exists a reduced automaton,
30 unique up to isomorphism, recognizing L . This automaton \mathbb{A}_L can be computed
31 from any automaton recognizing L by an efficient algorithm called minimization
32 and is called the *minimal automaton* of L .

\mathbb{A}_L

33 The classes of the equivalence relation $p \sim q \Leftrightarrow p \preceq q$ and $q \preceq p$ are called
34 *components* of \mathbb{A} . A component C is *trivial* if $C = \{p\}$ for some state p such that
35 $pa \neq p$ for any $a \in \Sigma$, and is a *sink* if $C\Sigma \subseteq C$. It is clear that each automaton
36 has at least one sink and sinks are never trivial. The *component graph* $\Gamma(\mathbb{A})$ of
37 \mathbb{A} is an edge-labelled directed graph (V, E, ℓ) along with a mapping $c : Q \rightarrow V$
38 where V is the set of the \sim -classes of \mathbb{A} , the mapping c associates to each state
39 q its class $q/\sim = \{p : p \sim q\}$ and for two classes p/\sim and q/\sim there exists
40 an edge from p/\sim to q/\sim labelled by $a \in \Sigma$ if and only if $p'a = q'$ for some
41 $p' \sim p, q' \sim q$. It is known that the component graph can be constructed from \mathbb{A}

(trivial) components
and sinks

1 in linear time. Note that the mapping c is redundant but it gives a possibility for
2 determining whether $p \sim q$ holds in constant time on a RAM machine, provided
3 $Q = [n]$ for some $n > 0$ and c is stored as an array.

4 When $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ is an automaton, its *transformation semigroup* $\mathcal{T}(\mathbb{A})$
5 consists of the set of transformations of Q induced by nonempty words, i.e.
6 $\mathcal{T}(\mathbb{A}) = \{u^{\mathbb{A}} : u \in \Sigma^+\}$ where $u^{\mathbb{A}} : Q \rightarrow Q$ is the transformation defined as
7 $q \mapsto qu$. The *state complexity* $\text{stc}(L)$ of a regular language L is the number of
8 states of its minimal automaton \mathbb{A}_L while its *syntactic complexity* $\text{syc}(L)$ is the
9 cardinality of its transformation semigroup $\mathcal{T}(\mathbb{A}_L)$. The *syntactic complexity* of
10 a *class* of languages C is a function $f : \mathbb{N} \rightarrow \mathbb{N}$ defined as

$$f(n) = \max\{\text{syc}(L) : L \in C, \text{stc}(L) \leq n\},$$

11 i.e. $f(n)$ is the maximal size that the transformation semigroup of a minimal
12 automaton of a language belonging to C can have, provided the automaton has
13 at most n states.

14 3 Semigroups of nonpermutational transformations

15 Observe that NP_n is not a semigroup (i.e., not closed under composition) when
16 $n > 2$. Indeed, if $f = (2, 3, 3)$ and $g = (1, 1, 2)$ (both being nonpermutational),
17 then their product $fg = (1, 2, 2)$ is permutational with $\{1, 2\}fg = \{1, 2\}$. (See
18 Figure 1.)

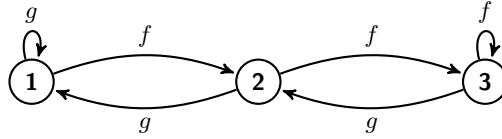


Fig. 1: f and g are nonpermutational, fg is permutational

19 Thus, the following question is nontrivial: how large a subsemigroup of T_n , which
20 consists only of nonpermutational transformations can be? The obvious upper
21 bound is n^n , the size of T_n .

22 **As a first step we give an upper bound of n^{n-2} .** Observe that the following
23 are equivalent for a function $f : [n] \rightarrow [n]$:

- 24 i) f is nonpermutational;
- 25 ii) the graph of f is a rooted tree with edges directed towards the root, and
26 with a loop edge attached on the root;
- 27 iii) f^ω , the unique idempotent power of f is a constant function.

1 Here “the graph of f ” is of course the directed graph Γ_f on vertex set $[n]$ and
2 with (i, j) being an edge iff $if = j$.

3 Indeed, assume f is nonpermutational. Let X be the set of all nodes of Γ_f lying
4 on some closed path. (Since each node of the finite graph Γ_f has outdegree 1, X
5 is nonempty.) Then $Xf = X$, thus $|X| = 1$, i.e. f has a unique fixed point $\text{Fix}(f)$ $\text{Fix}(f)$
6 and apart from the loop edge on $\text{Fix}(f)$, Γ_f is a directed acyclic graph (DAG)
7 with each node distinct from $\text{Fix}(f)$ having outdegree 1 – that is, a tree rooted
8 at $\text{Fix}(f)$, with edges directed towards the root, showing i) \rightarrow ii). Then f^n is a
9 constant function with value $\text{Fix}(f)$, showing ii) \rightarrow iii); finally, if $Xf = X$ for
10 some nonempty $X \subseteq [n]$, then $Xf^\omega = X$, showing $|X| = 1$ since the image of
11 f^ω is a singleton.

12 Now from ii) we get that the members of NP_n are exactly the rooted trees with
13 edges directed towards the root on which a loop edge is attached – we call such a
14 graph an inverted looped arborescence¹, or ILA for short. By Cayley’s theorem
15 on the number of labeled rooted trees over n nodes, the number of all ILAs (i.e.,
16 $|NP_n|$) is n^{n-2} , giving a slightly better upper bound.

17 **To achieve an upper bound of $n!$** , suppose $S \subseteq NP_n$ is a subsemigroup of
18 T_n . For $i \in [n]$, let $S_i \subseteq S$ be the subsemigroup $\{f \in S : \text{Fix}(f) = i\}$ of S . Note
19 that S_i is indeed a semigroup: by assumption, S is closed under composition and
20 consists of nonpermutational transformations only, moreover, if i is the common
21 (unique) fixed point of f and g , then it is also a fixed point of fg as well, thus
22 S_i is closed under composition.

23 **We give an upper bound of $(n - 1)!$ for $|S_i|$, $i \in [n]$** , yielding $|S| \leq n!$. To
24 this end, let Γ_i be the graph on vertex set $[n]$ with (j, k) being an edge iff $jf = k$
25 for some $f \in S_i$. Then, apart from the trivial case when $S_i = \emptyset$, (i, i) is an edge in
26 Γ_i , moreover i is a sink (since $if = i$ for each $f \in S_i$). Note that in the case when
27 $S_i = \emptyset$, $|S_i| = 0 \leq (n - 1)!$ clearly holds. Observe that Γ_i is transitive, since if
28 (j, k) and (k, ℓ) are edges of Γ_i , then $jf = k$ and $kg = \ell$ for some $f, g \in S_i$; since
29 S_i is a semigroup, fg is also in S_i thus (j, ℓ) is also an edge in Γ_i . Now assume
30 some node $j \in [n]$ is in a nontrivial strongly connected component (SCC) of
31 Γ_i , i.e. j lies on some closed path. By transitivity, (j, j) is an edge of Γ_i , thus
32 $jf = j$ for some $f \in S_i$, thus $j = i$ since $i = \text{Fix}(f)$ is the unique fixed point of
33 $f \in S_i$. Hence by dropping the edge (i, i) we get a DAG again, thus Γ_i (viewed
34 as a relation) is a strict partial ordering of $[n]$ with largest element i . Let \prec_i
35 stand for this partial ordering, i.e., let $j \prec_i k$ if and only if $j \neq i$ and $jf = k$
36 for some $f \in S_i$. Let us also fix some arbitrary total ordering $<_i$ extending \prec_i

¹ For comparison, an arborescence is a rooted tree with its edges being directed *away* from the root. Adding a loop edge to the root yields a “looped arborescence”. However, we were unable to find a name in the literature for transposes of arborescences – if there exists some, it would be better to use that name instead of “nonpermutational”. Coining the term “ecnecserobra” is out of question. “Ultimately constant” would be also an option. We would be thankful for the referees to point out an existing term in the literature.

1 and write the members of $[n]$ in the order $a_{i,1} <_i a_{i,2} <_i \dots <_i a_{i,n} = i$. Then
2 for any $f \in S_i$ and $1 \leq j < n$ we have $a_{i,j} <_i a_{i,j}f$, and $a_{i,n}f = a_{i,n}$. Since the
3 number of functions $f : [n] \rightarrow [n]$ satisfying this constraint is $(n-1)!$ ($a_{i,1}$ can
4 get $(n-1)$ different possible values, $a_{i,2}$ can get $(n-2)$ etc.), we immediately
5 get $|S_i| \leq (n-1)!$ as well, yielding $|S| \leq n!$.

6 **Via a somewhat cumbersome case analysis we can sharpen this upper**
7 **bound to $n((n-1)! - (n-3)!)$.** Without loss of generality assume that S_n is
8 (one of) the largest of the semigroups S_i and that $<_n$ is the usual ordering $<$ of
9 $[n]$ (we can achieve this by a suitable bijection).

10 **Lemma 1.** *Suppose for each $i < j$ and $k < \ell$ with $i \neq k$ there exists a function*
11 *$f \in S_n$ with $if = j$ and $kf = \ell$.*

12 *Then the following holds for each $i, j \in [n]$ and $f \in S_i$:*

- 13 i) *if $j < i$, then $j < jf$;*
- 14 ii) *if $i \leq j$, then $jf = i$.*

15 *Proof.* By assumption, the statements clearly hold for $i = n$. Let $i < n$ be
16 arbitrary and $f \in S_i$ a transformation. Clearly $if = i$ by the definition of S_i .
17 Also, $nf < n$ since $i \neq n$ is the unique fixed point of f .

18 Suppose $jf < j$ for some j . Then $jf = nf$ has to hold: if $jf \neq nf$, then
19 by assumption $jfg = j$ and $nfg = n$ for some $g \in S_n$, thus both j and n
20 are distinct fixed points of fg , a contradiction. (See Figure 2.) This implies in
21 particular that $j \leq jf$ for each $j < nf$.

22 Also, if $nf < i$, then $nfg = i$ and $ig = n$ for some $g \in S_n$, in which case $fgfg$ has
23 two distinct fixed points n and i , a contradiction. (See Figure 2.) Thus $i \leq nf$.

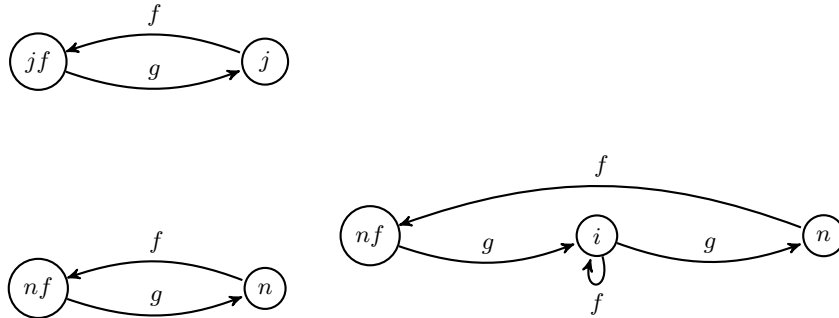


Fig. 2: Left: if $jf < j$, $jf \neq nf$, then fg has two fixed points. Right: If $nf < i$, then $fgfg$ has two fixed points

1 Assume $i < nf$. Then (since $nf^n = i < nf$) there is some $k > 0$ such that
2 $nf^{k+1} < nf$. If k is chosen to be the smallest possible such k , then $nf \leq nf^k$,
3 yielding $(nf^k)f < nf \leq nf^k$, a contradiction (by $(nf^k)f < nf^k$, it should hold
4 that $(nf^k)f = nf$, see Figure 3). Hence $i = nf$ is the unique fixed point of f
and for each $j < i$, $j < jf$ indeed has to hold, showing i).

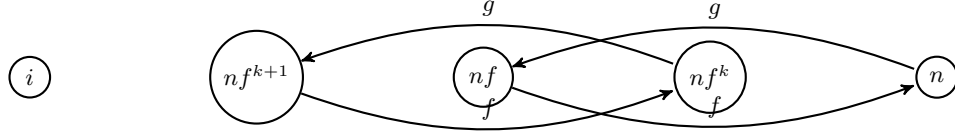


Fig. 3: If $i < nf$, then fg has two distinct fixed points

5
6 Finally, assume $i < j < jf$. Then $ig = j$ and $jfg = n$ for some $g \in S_n$ (if $jjf = n$,
7 then this latter case always gets satisfied, otherwise it's by assumption on S_n),
and $fgfg$ has two distinct fixed points j and n . Thus we have indeed shown that

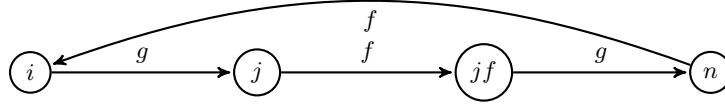


Fig. 4: If $i < j < jf$, then $fgfg$ has two distinct fixed points

8
9 $nf = i$ is the unique fixed point of f , $j < jf$ for each $i < j$ and $jjf = i$ for each
10 $i \leq j \leq n$. □

11 Lemma 1 has the following corollary:

12 **Theorem 1.** *The cardinality of any subsemigroup S of T_n consisting only of*
13 *nonpermutational transformations is at most $n((n-1)! - (n-3)!)$.*

14 *Proof.* As before, let S_i stand for $\{f \in S : \text{Fix}(f) = i\}$ and without loss of
15 generality we assume that amongst them S_n is one of the largest one, moreover
16 $<_n$ coincides with $<$.

17 If for each $i < j$ and $i' < j'$ with $i \neq i'$ there is some $f \in S_n$ with $if = j$ and
18 $i'f = j'$, then by Lemma 1 S_i can consist of at most $(n-1)(n-2) \dots (n-i-1) =$
19 $\frac{(n-1)!}{(n-i)!}$ elements (we have to choose for each $j < i$ a larger integer and that's all
20 since the other elements have to be mapped to i). Also $|S_n| \leq (n-1)!$ as well.

1 Summing up we get an upper bound for these semigroups

$$\sum_{i=1}^n \frac{(n-1)!}{(n-i)!} = (n-1)! \sum_{j=0}^{n-1} \frac{1}{j!} = \lfloor e(n-1)! \rfloor,$$

2 which comes from the facts that $e = \sum_{j=0}^{\infty} \frac{1}{j!}$ and $(n-1)! \sum_{j=n}^{\infty} \frac{1}{j!} < 1$.

3 For the other case, suppose there exists an $i < j$ and an $i' < j'$ with $i \neq i'$ such
4 that $if = j$ and $i'f = j'$ do not both hold for any $f \in S_n$. Still, $i < if$ for each
5 $i < n$ and $nf = n$, by definition of S_n and the assumption \leq_n . The number
6 of such functions satisfying both $if = j$ and $i'f = j'$ is $\frac{(n-1)!}{(n-i)(n-j)} \geq (n-3)!$,
7 hence the size of S_n is upper-bounded by $(n-1)! - (n-3)!$. Since S_n is the
8 largest amongst the S_i 's and S is the disjoint union of them we get the claimed
9 upper bound $n((n-1)! - (n-3)!)$. \square

10 We note that the construction for the first case, yielding the upper bound $\lfloor e(n-1)! \rfloor$
11 indeed constructs a semigroup B which is exactly the semigroup from [2]
12 conjectured there to be a candidate for the maximal-size such subsemigroup.

13 Our proof can be viewed as a support for this conjecture and can be reformalized
14 as follows: if there exists some i such that many transformations share this fixed
15 point i , then the size of S is upper-bounded by $\lfloor e(n-1)! \rfloor$ and S is isomorphic
16 to a subsemigroup of B . The question is, whether one can construct a larger
17 semigroup by putting not too many functions sharing a common fixed point. We
18 also conjecture that B is a good candidate for a maximal-size subsemigroup of
19 T_n consisting of nonpermutational transformations only.

20 4 Application to syntactic complexity

21 A language L is *definite* if there exists a constant $k \geq 0$ such that for any
22 $x \in \Sigma^*$, $y \in \Sigma^k$ we have $xy \in L \Leftrightarrow y \in L$ and is *generalized definite* if there
23 exists a constant $k \geq 0$ such that for any $x_1, x_2 \in \Sigma^k$ and $y \in \Sigma^*$ we have
24 $x_1yx_2 \in L \Leftrightarrow x_1x_2 \in L$.

25 These are both subclasses of the star-free languages, i.e. can be built from the
26 singletons with repeated use of the concatenation, finite union and complemen-
27 tation operations. It is known that the following decision problem is complete
28 for **PSPACE**: given a regular language L with its minimal automaton, is L
29 star-free? In contrast, the question for these subclasses above are tractable.

30 Minimal automata of these languages possess a characterization in terms of
31 *forbidden patterns*. In our setting, a pattern is an edge-labelled, directed graph
32 $P = (V, E, \ell)$, where V is the set of vertices, $E \subseteq V^2$ is the set of edges, and
33 $\ell : E \rightarrow \mathcal{X}$ is a labelling function which assigns to each edge a variable. An
34 automaton $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ admits a pattern $P = (V, E, \ell)$ if there exists

admitting/avoiding
a pattern

- 1 an *injective* mapping $f : V \rightarrow Q$ and a map $h : \mathcal{X} \rightarrow \Sigma^+$ such that for each
2 $(u, v) \in E$ labelled x we have $f(u) \cdot h(x) = f(v)$. Otherwise \mathbb{A} *avoids* P .
3 As an example, consider the pattern P_d on Figure 5.



Fig. 5: Patterns for definite and generalized definite languages.

4 A reduced automaton avoids P_d if and only if it recognizes a definite language.
5 Indeed, a language L is definite iff its syntactic semigroup satisfies the identity
6 $yx^\omega = x^\omega$. Now assume $L(\mathbb{A})$ admits P_d with $px = p$ and $qx = q$ with $p \neq q$
7 and $x \in \Sigma^+$. If $q_0x^\omega = p$, then $q_0x^\omega \neq q_0yx^\omega$ for a (nonempty) word y with
8 $q_0y = q$. If $q_0x^\omega \neq p$, then $q_0x^\omega \neq q_0yx^\omega$ for a (nonempty) y with $q_0y = p$, thus
9 the identity is not satisfied. For the other direction, if the transition semigroup of
10 an automaton \mathbb{A} does not satisfy $x^\omega = yx^\omega$, then $p_0x_0^\omega \neq p_0yx_0^\omega$ for some p_0, x_0
11 and y ; choosing $p = p_0x_0^\omega$, $q = p_0y$ and $x_0 = x^\omega$ witnesses admittance of P_d .
12 (For a more detailed discussion see e.g. [2].)

13 Observe that avoiding P_d is equivalent to state that each nonempty word induces
14 a transformation with at most one fixed point, which is further equivalent to state
15 that each nonempty word induces a non-permutational transformation: for each
16 nonempty u , the word $u^{|Q|!}$ fixes each state belonging to a nontrivial component
17 of the graph of u , hence u also can have only one state in a nontrivial component,
18 i.e. u induces a nonpermutational transformation. (Again, see [2] for a different
19 formulation.²)

20 Thus Theorem 1 has the following byproduct:

21 **Corollary 1.** *The syntactic complexity of the definite languages is at most $n((n-1)! - (n-3)!)$.*
22

23 4.1 The case of generalized definite languages

24 In this subsection we show that the syntactic complexity of definite and gen-
25 eralized definite languages coincide. To this end we study the structure of the

² Since – up to our knowledge – [2] has not been published yet in a peer-reviewed journal or conference proceedings, we include a proof of this fact. Nevertheless, we do not claim this result to be ours, by any means.

1 minimal automata of the members of the latter class. In the process we give a
2 (to our knowledge) new (but not too surprising) characterization of the minimal
3 automata of generalized definite languages, leading to an **NL**-completeness re-
4 sult of the corresponding decision problem, as well as a low-degree polynomial
5 deterministic algorithm.

6 Our first observation is the following characterization:

7 **Theorem 2.** *The following are equivalent for a reduced automaton \mathbb{A} :*

- 8 *i) \mathbb{A} avoids P_g .*
- 9 *ii) Each nontrivial component of \mathbb{A} is a sink, and for each nonempty word u
10 and sink C of \mathbb{A} , the transformation $u|_C : C \rightarrow C$ is non-permutational.*
- 11 *iii) \mathbb{A} recognizes a generalized definite language.*

12 *Proof.* Let $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ be a reduced automaton.

13 **i)→ii).** Suppose \mathbb{A} avoids P_g . Suppose that $u|_C$ is permutational for some sink
14 C and word $u \in \Sigma^+$. Then there exists a set $D \subseteq C$ with $|D| > 1$ such that
15 u induces a permutation on D . Then, $x = u^{|D|}$ is the identity on D . Choosing
16 arbitrary distinct states $p, q \in D$ and a word y with $py = q$ (such y exists since p
17 and q are in the same component of \mathbb{A}), we get that \mathbb{A} admits P_g by the (p, q, x, y)
18 defined above, a contradiction. Hence, $u|_C$ is non-permutational for each sink C
19 and word $u \in \Sigma^+$.

20 Now assume there exists a nontrivial component C which is not a sink. Then,
21 $pu = p$ for some $p \in C$ and word $u \in \Sigma^+$. Since C is not a sink, there exists
22 a sink $C' \neq C$ reachable from p (i.e. all of its members are reachable from p).
23 Since u induces a non-permutational transformation on C' , $x = u^{|C'|}$ induces a
24 constant function on C' . Let q be the unique state in the image of $x|_{C'}$. Since
25 C' is reachable from p , there exists some nonempty word y such that $py = q$.
26 Hence, $px = p$, $qx = q$, $py = q$ and \mathbb{A} admits P_g , a contradiction.

27 **ii)→iii).** Suppose the condition of ii) holds. We show that $L = L(\mathbb{A})$ is gen-
28 eralized definite. By the assumption, q_0u belongs to a sink for any u with
29 $|u| \geq |Q|$. On the other side, viewing a sink C as a (reduced) automaton
30 $\mathbb{C} = (C, \Sigma, \delta|_C, p, F \cap C)$ with p being an arbitrary state of C we get that the
31 transition semigroup of \mathbb{C} consists of nonpermutational transformations only, i.e.
32 $L(\mathbb{C})$ is k -definite for some $k = k_C$. Hence choosing n to be the maximum of $|Q|$
33 and the values k_C with C being a sink we get that L is n -generalized definite
34 (since the length- n prefix of u determines the sink C to which q_0u belongs and
35 the length- n suffix of u , once we know C , determines the unique state in Cu).

36 **iii)→i).** Suppose $L(\mathbb{A})$ is generalized definite. Then its syntactic semigroup sat-
37 isfies $x^\omega y x^\omega = x^\omega$ (see e.g. [14]).

38 Now assume \mathbb{A}_L admits P_g with $px = p$, $qx = q$ and $py = q$ for the nonempty
39 words x, y and different states p, q . Then $px^\omega = p$ and $px^\omega y x^\omega = q$, and the
40 identity is not satisfied, thus L is not generalized definite. \square

1 **Complexity issues** We now take a slight excursion.

2 Using the characterization given in Theorem 2, we study the complexity of the
 3 following decision problem GENDEF: given a finite automaton \mathbb{A} , is $L(\mathbb{A})$ a gen-
 4 eralized definite language?

5 **Theorem 3.** *Problem GENDEF is **NL**-complete.*

6 *Proof.* First we show that GENDEF belongs to **NL**. By [3], minimizing a DFA
 7 can be done in nondeterministic logspace. Thus we can assume that the input
 8 is already minimized, since the class of (nondeterministic) logspace computable
 9 functions is closed under composition.

10 Consider the following algorithm:

- 11 1. Guess two different states p and q .
- 12 2. Let $s := p$.
- 13 3. Guess a letter $a \in \Sigma$. Let $s := sa$.
- 14 4. If $s = q$, proceed to Step 5. Otherwise go back to Step 3.
- 15 5. Let $p' := p$ and $q' := q$.
- 16 6. Guess a letter $a \in \Sigma$. Let $p' := p'a$ and $q' := q'a$.
- 17 7. If $p = p'$ and $q = q'$, accept the input. Otherwise go back to Step 6.

18 The above algorithm checks whether \mathbb{A} admits P_g : first it guesses $p \neq q$, then
 19 in Steps 2–4 it checks whether q is accessible from p , and if so, then in Steps
 20 5–7 it checks whether there exists a word $x \in \Sigma^+$ with $px = p$ and $qx = q$.
 21 Thus it decides³ the complement of GENDEF, in nondeterministic logspace; since
 22 **NL** = co**NL**, we get that GENDEF \in **NL** as well.

23 For **NL**-completeness we recall from [8] that the reachability problem for DAGs
 24 (DAG-REACH) is complete for **NL**: given a directed acyclic graph $G = (V, E)$
 25 on $V = [n]$ with $(i, j) \in E$ only if $i < j$, is n accessible from 1? We give a
 26 logspace reduction from DAG-REACH to GENDEF as follows. Let $G = ([n], E)$
 27 be an instance of DAG-REACH. For a vertex $i \in [n]$, let $N(i) = \{j : (i, j) \in E\}$
 28 stand for the set of its neighbours and let $d(i) = |N(i)| < n$ denote the outdegree
 29 of i . When $j \in [d(i)]$, then the j th neighbour of i , denoted $n(i, j)$ is simply the
 30 j th element of $N(i)$ (with respect to the usual ordering of integers of course).
 31 Note that for any $i \in [n]$ and $j \in [d(i)]$ both $d(i)$ and the $n(i, j)$ (if exists) can
 32 be computed in logspace.

33 We define the automaton $\mathbb{A} = ([n+1], [n], \delta, 1, \{n+1\})$ where

$$\delta(i, j) = \begin{cases} n+1 & \text{if } (i = n+1) \text{ or } (j = n) \text{ or } (i < n \text{ and } d(i) < j); \\ 1 & \text{if } i = n \text{ and } j < n; \\ n(i, j) & \text{otherwise.} \end{cases}$$

³ Note that in this form, the algorithm can enter an infinite loop which fits into the definition of nondeterministic logspace. Introducing a counter and allowing at most n steps in the first cycle and at most n^2 in the second we get a nondeterministic algorithm using logspace and polytime, as usual.

1 Note that \mathbb{A} is indeed an automaton, i.e. $\delta(i, j)$ is well-defined for each i, j .

2 We claim that \mathbb{A} admits P_g if and only if n is reachable from 1 in G . Observe
3 that the underlying graph of \mathbb{A} is G , with a new edge $(n, 1)$ and with a new
4 vertex $n + 1$, which is a neighbour of each vertex. Hence, $\{n + 1\}$ is a sink of \mathbb{A}
5 which is reachable from all other states. Thus \mathbb{A} admits P_g if and only if there
6 exists a nontrivial component of \mathbb{A} which is different from $\{n + 1\}$. Since in G
7 there are no cycles, such component exists if and only if the addition of the edge
8 $(n, 1)$ introduces a cycle, which happens exactly in the case when n is reachable
9 from 1. Note that it is exactly the case when $1x = 1$ for some word $x \in \Sigma^+$.

10 What remains is to show that the *reduced* form \mathbb{B} of \mathbb{A} admits P_g if and only
11 if \mathbb{A} does. First, both 1 and $n + 1$ are in the connected part \mathbb{A}' of \mathbb{A} , and are
12 distinguishable by the empty word (since $n + 1$ is final and 1 is not). Thus, if \mathbb{A}
13 admits P_g with $1x = 1$ and $(n + 1)x = n + 1$ for some $x \in \Sigma^+$, then \mathbb{B} admits P_g
14 with $h(1)x = h(1)$ and $h(n + 1)x = h(n + 1)$ (with h being the homomorphism
15 from the connected part of \mathbb{A} onto its reduced form). For the other direction,
16 assume $h(p)x_0 = h(p)$ for some state $p \neq n + 1$ (note that since $n + 1$ is the
17 only final state, $p \neq n + 1$ if and only if $h(p) \neq h(n + 1)$). Let us define the
18 sequence p_0, p_1, \dots of states of \mathbb{A} as $p_0 = p$, $p_{t+1} = p_t x_0$. Then, for each $i \geq 0$,
19 $h(p_i) = h(p)$, thus $p_i \in [n]$. Thus, there exist indices $0 \leq i < j$ with $p_i = p_j$,
20 yielding $p_i x_0^{j-i} = p_i$, thus \mathbb{A} admits P_g with $p = p_i$, $q = n + 1$, $x = x_0^{j-i}$ and
21 $y = n$.

22 Hence, the above construction is indeed a logspace reduction from DAG-REACH
23 to the complement of GENDEF, showing **NL**-hardness of the latter; applying
24 **NL** = co**NL** again, we get **NL**-hardness of GENDEF itself. \square

25 It is worth observing that the same construction also shows **NL**-hardness (thus
26 completeness) of the problem whether the input automaton accepts a definite
27 language.

28 Thus, the complexity of the problem is characterized from the theoretic point
29 of view. However, nondeterministic algorithms are not that useful in practice.
30 Since **NL** \subseteq **P**, the problem is solvable in polynomial time – now we give an
31 efficient (quadratic) deterministic decision algorithm:

- 32 1. Compute $\mathbb{A}' = (Q, \Sigma, \delta, q_0, F)$, the reduced form of the input automaton \mathbb{A} .
- 33 2. Compute $\Gamma(\mathbb{A}')$, the component graph of \mathbb{A}' .
- 34 3. If there exists a nontrivial, non-sink component, reject the input.
- 35 4. Compute $\mathbb{B} = \mathbb{A}' \times \mathbb{A}'$ and $\Gamma(\mathbb{B})$.
- 36 5. Check whether there exist a state (p, q) of \mathbb{B} in a nontrivial component (of
37 \mathbb{B}) for some $p \neq q$ with p being in the same sink as q in \mathbb{A} . If so, reject the
38 input; otherwise accept it.

39 The correctness of the algorithm is straightforward by Theorem 2: after mini-
40 mization (which takes $\mathcal{O}(n \log n)$ time) one computes the component graph of

the reduced automaton (taking linear time) and checks whether there exists a nontrivial component which is not a sink (taking linear time again, since we already have the component graph). If so, then the answer is NO. Otherwise one has to check whether there is a (sink) component C and a word $x \in \Sigma^+$ such that $f_x|_C$ has at least two different fixed points. Now it is equivalent to ask whether there is a state (p, q) in $\mathbb{A}' \times \mathbb{A}'$ with p and q being in the same component and a word $x \in \Sigma^+$ with $(p, q)x = (p, q)$. This is further equivalent to ask whether there is a (p, q) with p, q being in the same sink such that (p, q) is in a nontrivial component of \mathbb{B} . Computing \mathbb{B} and its components takes $\mathcal{O}(n^2)$ time, and (since we still have the component graph of \mathbb{A}) checking this condition takes constant time for each state (p, q) of \mathbb{B} , the algorithm consumes a total of $\mathcal{O}(n^2)$ time.

Hence we have an upper bound concluding this excursion:

Theorem 4. *Problem GENDEF can be solved in $\mathcal{O}(n^2)$ deterministic time in the RAM model of computation.*

Syntactic complexity In [2] it has been shown that the class of definite languages has syntactic complexity $\geq \lfloor e \cdot (n-1)! \rfloor$, thus the same lower bound also applies for the larger class of generalized definite languages.

Theorem 5. *The syntactic complexity of the definite and that of the generalized definite languages coincide.*

Proof. It suffices to construct for an arbitrary reduced automaton $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ recognizing a generalized definite language a reduced automaton $\mathbb{B} = (Q, \Delta, \delta', q_0, F')$ for some Δ recognizing a definite language such that $|\mathcal{T}(\mathbb{A})| \leq |\mathcal{T}(\mathbb{B})|$.

By Theorem 2, if $L(\mathbb{A})$ is generalized definite and \mathbb{A} is reduced, then Q can be partitioned as a disjoint union $Q = Q_0 \uplus Q_1 \uplus \dots \uplus Q_c$ for some $c > 0$ such that each Q_i with $i \in [c]$ is a sink of \mathbb{A} and Q_0 is the (possibly empty) set of those states that belong to a trivial component. Without loss of generality we can assume that $Q = [n]$ and $Q_0 = [k]$ for some n and k , and that for each $i \in [k]$ and $a \in \Sigma$, $i < ia$. The latter condition is due to the fact that reachability restricted to the set Q_0 of states in trivial components is a partial ordering of Q_0 which can be extended to a linear ordering. Clearly, if Q_0 is nonempty, then by connectedness $q_0 = 1$ has to hold; otherwise $c = 1$ and we again may assume $q_0 = 1$. Also, $Q_i \Sigma \subseteq Q_i$ for each $i \in [c]$, and let $|Q_1| \leq |Q_2| \leq \dots \leq |Q_c|$.

Then, each transformation $f : Q \rightarrow Q$ can be uniquely written as the source tupling $[f_0, \dots, f_c]$ of some functions $f_i : Q_i \rightarrow Q$ with $f_i : Q_i \rightarrow Q_i$ for $0 < i \leq c$. For any $[f_0, \dots, f_c] \in \mathcal{T} = \mathcal{T}(\mathbb{A})$ the following hold: $f_0(i) > i$ for each $i \in [k]$, and f_j is non-permutational on Q_j for each $j \in [c]$. For $k = 0, \dots, c$, let \mathcal{T}_k stand for the set $\{f_k : f \in \mathcal{T}\}$ (i.e. the set of functions $f|_{Q_k}$ with $f \in \mathcal{T}$). Then, $|\mathcal{T}| \leq \prod_{0 \leq k \leq c} |\mathcal{T}_k|$.

1 If $|Q_c| = 1$, then all the sinks of \mathbb{A} are singleton sets. Thus there are at most
2 two sinks, since if C and D are singleton sinks whose members do not differ in
3 their finality, then their members are not distinguishable, thus $C = D$ since \mathbb{A} is
4 reduced. Such automata recognize reverse definite languages, having a syntactic
5 semigroup of size at most $(n-1)!$ by [2], thus in that case \mathbb{B} can be chosen to an
6 arbitrary definite automaton having n state and a syntactic semigroup of size
7 at least $\lfloor e(n-1)! \rfloor$ (by the construction in [2], such an automaton exists). Thus
8 we may assume that $|Q_c| > 1$. (Note that in that case Q_c contains at least one
9 final and at least one non-final state.)

10 Let us define the sets \mathcal{T}'_k of functions $Q_i \rightarrow Q$ as \mathcal{T}'_0 is the set of all elevating
11 functions from $[k]$ to $[n]$, $\mathcal{T}'_c = \mathcal{T}_c$ and for each $0 < k < c$, $\mathcal{T}'_k = Q_c^{Q_k}$. Since
12 $\mathcal{T}_k \subseteq Q_c^{Q_k}$ and $|Q_k| \leq |Q_c|$ for each $k \in [c]$, we have $|\mathcal{T}_k| \leq |\mathcal{T}'_k|$ for each
13 $0 \leq k \leq c$. Thus defining $\mathcal{T}' = \{[f_0, \dots, f_c] : f_i \in \mathcal{T}'_i\}$ it holds that $|\mathcal{T}| \leq |\mathcal{T}'|$.

14 We define \mathbb{B} as $(Q, \mathcal{T}', \delta', q_0, F)$ with $\delta'(q, f) = f(q)$ for each $f \in \mathcal{T}'$. We show
15 that \mathbb{B} is a reduced automaton avoiding P_d , concluding the proof.

16 First, observe that \mathbb{B} has exactly one sink, Q_c , and all the other states belong to
17 trivial components (since by each transition, each member of Q_0 gets elevated,
18 and each member of Q_i with $0 < i < c$ is taken into Q_c). Hence if \mathbb{B} admits
19 P_d , then $pt = p$ and $qt = q$ for some distinct pair $p, q \in Q_c$ of states and
20 $t = [t'_0, \dots, t'_c] \in \mathcal{T}'$. This is further equivalent to $pt'_c = p$ and $qt'_c = q$ for some
21 $p \neq q$ in Q_c and $t'_c \in \mathcal{T}'_c$. By definition of $\mathcal{T}'_c = \mathcal{T}_c$, there exists a transformation
22 of the form $t = [t_0, \dots, t_{c-1}, t'_c] \in \mathcal{T}$ induced by some word x , thus $px = p$ and
23 $qx = q$ both hold in \mathbb{A} , and since p, q are in the same sink, there also exists a
24 word y with $py = q$. Hence \mathbb{A} admits P_g , a contradiction.

25 Second, \mathbb{B} is connected. To see this, observe that each state $p \neq 1$ is reachable
26 from 1 by any transformation of the form $t = [f_p, t_1, \dots, t_c]$ where $f_p : [k] \rightarrow [n]$
27 is the elevating function with $1f_p = p$ and $if_p = n$ for each $i > 1$. Of course 1 is
28 also trivially reachable from itself, thus \mathbb{B} is connected.

29 Also, whenever $p \neq q$ are different states of \mathbb{B} , then they are distinguishable
30 by some word. To see this, we first show this for $p, q \in Q_c$. Indeed, since \mathbb{A} is
31 reduced, some transformation $t = [t_0, \dots, t_c] \in \mathcal{T}$ separates p and q (exactly one
32 of $pt = pt_c$ and $qt = qt_c$ belong to F). Since $\mathcal{T}_c = \mathcal{T}'_c$, we get that p and q are also
33 distinguishable by in \mathbb{B} by any transformation of the form $t' = [t'_0, \dots, t'_{c-1}, t_c] \in$
34 \mathcal{T}' . Now suppose neither p nor q belong to Q_c . Then, since $\{[t'_0, \dots, t'_{c-1}] : t'_i \in$
35 $\mathcal{T}'_i\} = Q_c^{Q \setminus Q_c}$, and $|Q_c| > 1$, there exists some $t = [t'_0, \dots, t'_{c-1}]$ with $pt \neq qt$,
36 thus any transformation of the form $[t'_0, \dots, t'_{c-1}, t_c] \in \mathcal{T}'$ maps p and q to
37 distinct elements of Q_c , which are already known to be distinguishable, thus so
38 are p and q . Finally, if $p \in Q_c$ and $q \notin Q_c$, then let $t_c \in \mathcal{T}_c$ be arbitrary and
39 $t' = [t'_0, \dots, t'_{c-1}] \in Q_c^{Q \setminus Q_c}$ with $qt' \neq pt_c$. Then $[t', t_c]$ again maps p and q to
40 distinct states of Q_c .

41 Thus \mathbb{B} is reduced, concluding the proof: \mathbb{B} is a reduced automaton recognizing
42 a definite language and having a syntactic semigroup \mathcal{T}' with $|\mathcal{T}'| \geq |\mathcal{T}|$. \square

5 Conclusion, further directions

The forbidden pattern characterization of generalized definite languages we gave is not surprising, based on the identities of the pseudovariety of (syntactic) semigroups corresponding to this variety of languages. Still, using this characterization one can derive efficient algorithms for checking whether a given automaton recognizes such a language. Though we could not compute an exact function for the syntactic complexity, we still managed to show that these languages are not “more complex” than definite languages under this metric. Also, we gave a new upper bound for that.

The exact syntactic complexity of definite languages is still open, as well as for other language classes higher in the dot-depth hierarchy – e.g. the locally (threshold) testable and the star-free languages.

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